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UNIT-ONE

SYMMETRY AND GROUP THEORY IN CHEMISTRY

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UNIT-ONE SYMMETRY & GROUP THEORY
(Analytical)

Introduction:

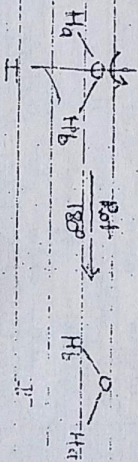
Symmetry is a very fascinating phenomenon. Nature is full of symmetry. From the great word symmetria, we measure together mathematical study or symmetry is called group theory.

Symmetry:

Any molecule or object is said to be symmetrical if it can take one or more equivalent configurations performing some geometrical manipulation on it.

e.g. H₂O molecule

In H₂O molecule relation by 180° about an axis passing through oxygen atom results on equivalent configuration. H₂O molecule is said to be symmetrical.



I & II are equivalent but not identical to understand symmetry concept should remember.

① symmetry element ② symmetry operation

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① Symmetry elements :-

A symmetry element is a geometrical entity such as a line or a plane or a point about which an operation of rotation or reflection or inversion is performed.

② Symmetry Operation :-

A symmetry operation is a movement of the molecule such that the resulting configuration of the molecule is indistinguishable from the original OR It is a geometrical manipulation when performed in a molecule always results an equivalent configuration. The molecule may assume an equivalent configuration or an identical configuration. e.g. In H_2O molecule rotation by 180° about an axis passing through the oxygen atom results an equivalent configuration hence it is said to be symmetry operation. In order to perform a symmetry operation molecule one should familiar with the following

① The shape of the molecule should be known.

② All the atoms in molecule assume to free state.

③ The centre of gravity or centre of the molecule should remain unchanged.

④ Folding of the molecule in a proper orientation is also important. There are five types of symmetry elements corresponding to symmetry operations.

sr No.	Symmetry elements	Symmetry operations
1	Proper axis of rotation (C_n)	Rotation by an angle $\frac{360^\circ}{n}$ about the axis.
2	Plane of symmetry (σ)	One or more reflections in a plane
3	Improper axis of rotation or rotation-reflection axis (S_n)	Rotation about the axis followed by reflection in a plane \perp to the rotation axis.
4	Centre of symmetry or inversion center (i)	Inversion of all atoms through the centre of symmetry
5	Identical element (E)	This operation leaves the molecule unchanged.

1 Proper axis of rotation (C_n)

axis passing through the molecule about which rotation operation is carried out result in an equivalent configuration

If n is represented by C_n

$n = \frac{360}{\theta}$ θ = Angle of rotation / symmetry angle

when $\theta = 180^\circ$

$n = \frac{360}{180} = 2$ i.e. $n=2$ C_2

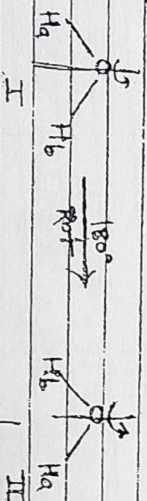
$\theta = 120^\circ$ $n = 3$ i.e. $n=3$ C_3

$\theta = 90^\circ$ $n = 4$ i.e. $n=4$ C_4

$\theta = 72^\circ$ $n = 5$ i.e. $n=5$ C_5

$\theta = 60^\circ$ $n = 6$ i.e. $n=6$ C_6

① e.g. H₂O molecule

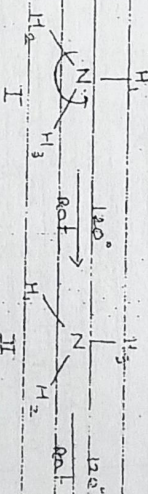


I & II are equivalent
I & III are identical

$n = \frac{360}{180} = C_2$

In H₂O molecule the rotation axis passing through oxygen atom rotation about this axis is 180 results an equivalent configuration hence water is said to have C₂ rotation axis or two fold rotational axis. In order to get identical molecule or configuration it should be rotated twice about the same axis.

② e.g. NH₃



I, II, III equivalent
I & IV identical

$n = \frac{360}{120} = C_3$

In ammonia molecule the rotation axis is passing through Nitrogen atom rotation about this axis results an equivalent configuration. Hence NH₃ molecule is said to have C₃ or 3 fold rotation axis.

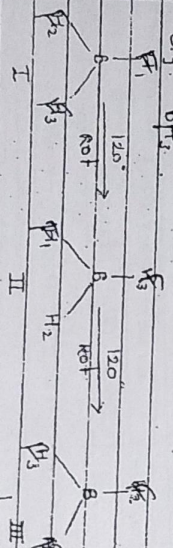
... .. Figure 10.1 Figure 10.2

① Type of rotational axis
Principal axis
② simple or secondary axis.

① Principal axis :
The highest fold rotational axis said to be principal axis. C_n
 $n = \text{order of rotation}$

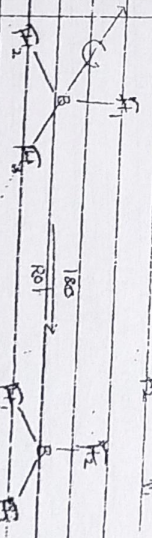
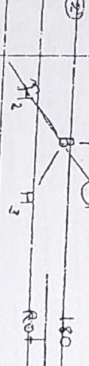
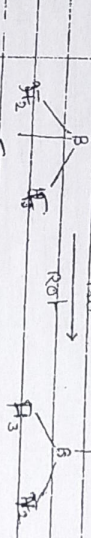
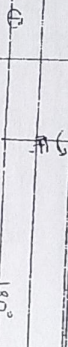
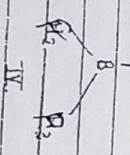
② Simple or secondary axis :

When principal axis are said to be secondary axis & always exist in multiple. The no. of C_2 axis always equal to order of principle axis ($n/2$)
e.g. BF_3



I, II, III are equivalent
I & IV are identical

$\theta = 120$
 $n = \frac{360}{120} = 3$



In above $\theta = 180^\circ$ $\therefore n = \frac{360}{180} = C_2$

In BF_3 molecule there are three C_2 i.e. $3C_2$ These are called secondary axis.

$C_3 = \text{principle axis}$

$3C_2 = \text{secondary axis}$

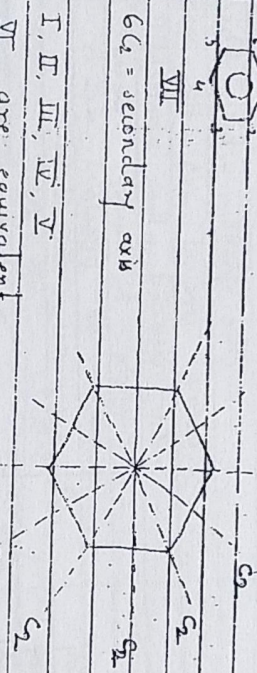
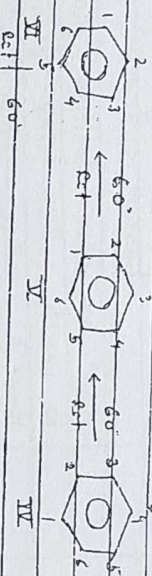
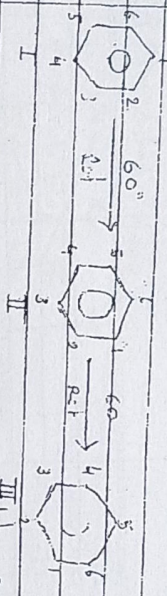
② C_6H_6 Benzene

In benzene molecule $\theta = 60^\circ$

$n = \frac{360}{60} = C_6$

$C_6 = \text{Principal axis}$

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$C_6 =$ secondary axis

I, II, III, IV, V, VI are equivalent
I & VII are identical

C_6 axis of symmetry is a principal axis in benzene. beside this there are six axis of two fold symmetry. three passing through centre of benzene & two opposite carbon atoms and three passing through the center of symmetry & center of two opposite edge.

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In all linear molecule the molecular axis is considered as C_∞ fold rotation axis since rotation by any fraction of angle results an equivalent configuration. In this molecule the angle of rotation $\theta = 0$

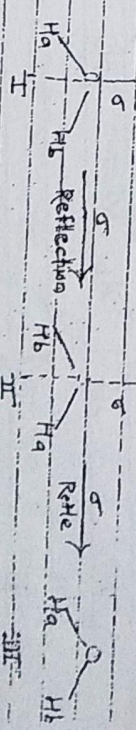
$$n = \frac{360^\circ}{\theta} = \infty \quad \text{i.e. } C_\infty$$

e.g. CO_2, H_2, HCl

② Plane of symmetry (σ)

A molecule is to be have plane of symmetry if reflection through that plane always result an equivalent configuration.

OR
A plane which bisects a molecule into two equal half which are mirror image to each other. It is represented by σ .



I & II are equivalent
I & III are identical

In H₂O molecule the plane is partially through the oxygen atom remains same while the hydrogen atom get exchanged. Thus H₂O molecule said to be have plane of symmetry.

Types of plane:

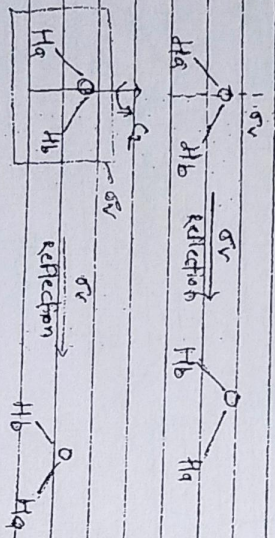
There are three types of plane

- ① Vertical plane (σ_v)
- ② Horizontal plane (σ_h)
- ③ Dihedral plane (σ_d)

① Vertical plane (σ_v)

The plane which is passing through C_∞ axis and one of secondary axis if present is said to be vertical plane. It is represented by σ_v.

e.g. H₂O molecule

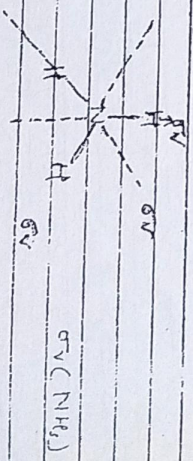


H₂O has two vertical planes perpendicular to each other one plane is passing through oxygen atom & another is molecular plane.

The plane which bisects all the atoms present in the molecule.

In general the vertical plane exist in multiple & always equal to n, i.e. order of principal axis.

e.g. NH₃, ammonia

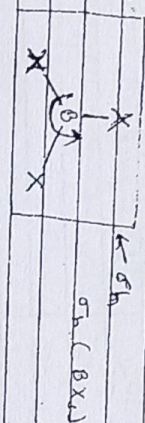


Ammonia has three vertical plane each vertical plane is passing through C_∞ axis i.e. each passing through one of the H atom & N atom hence there are three horizontal plane i.e. 3σ_v

② Horizontal Plane (σ_h)

The plane which is perpendicular to C_n i.e. principal axis is said to be horizontal plane. It is represented by σ_h .

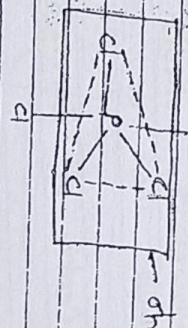
① e.g. BX_3 molecule



In BX_3 molecule the molecular plane is considered a horizontal plane since it is perpendicular to C_3 principle axis.

②

e.g. PCl_5 (TBP) σ_h T.B.P. - Trigonal bipyramidal

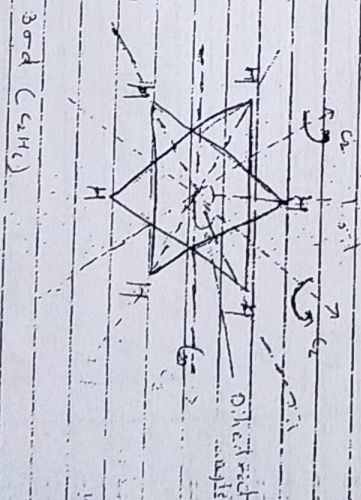
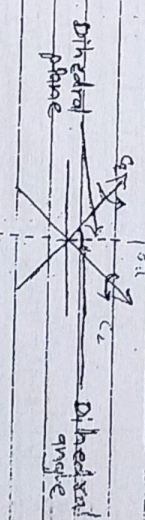


In PCl_5 plane which is passing through equatorial atom and a central atom is considered a horizontal plane since it is perpendicular to C_2 principle axis.

③ Dihedral Plane (σ_d)

The angle between two consecutive C_2 is known as dihedral angle. The plane which bisects the dihedral angle is called dihedral plane. It is represented by σ_d .

e.g. staggered ethane



④ Improper axis of symmetry (S_n)

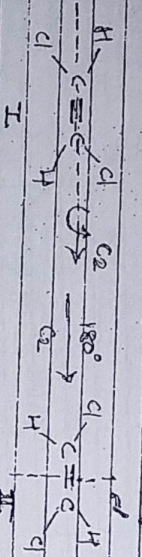
It is an axis passing through the molecule about which rotation followed by reflection perpendicular to rotation

or reflection followed by rotation perpendicular to the reflection.

If is represented by S_n , S_n is product of n operations which can be generated by doing combined operation. The operation results an equivalent configuration.

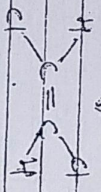
C_2 perpendicular to $C_2 = S_4$
 C_2 perpendicular to $C_2 = S_2$
 C_n perpendicular to $C_n = S_{2n}$

① e.g. Trans dichloro ethylene



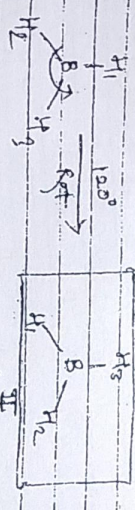
I & II are not equivalent
 I & III are identical

C_2 180° $C_2 = S_2$



In trans dichloro ethylene rotation by 180° about an axis passing through two carbon atoms will not result equivalent configuration while C_2 rotation followed by reflection leads to S_2 rotation result on equivalent configuration hence having S_2 improper axis.

② e.g. BH₃ molecule



str. I, II & III are equivalent.

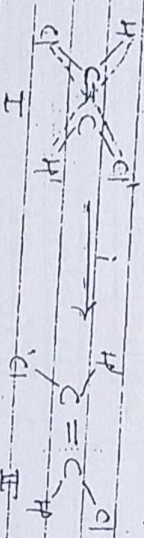
C_3 120° to $C_3 = S_6$

In BH₃ molecule rotation by 120° about an axis passing through B atom results an equivalent configuration while reflection followed by reflection leads to rotation results same equivalent configuration.

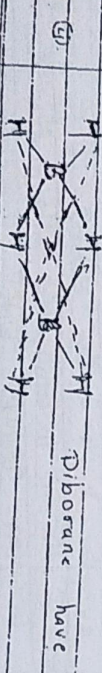
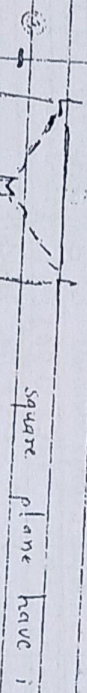
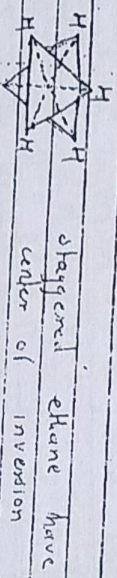
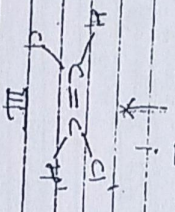
4) Centre of Inversion :-

A molecule said to have centre of inversion if all the straight line passing through centre of the molecule meet similar atoms at equal distance from the centre or. If is a point lie at exactly center of the molecule about which all the atoms present in the molecule are inverted.

to result equivalent configuration
 If is represented by (i) two consecutive inversion always result identical configuration.
 e.g. trans dichloroethylene.



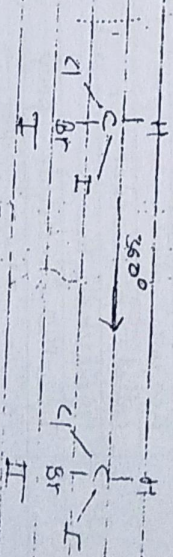
I & II are equivalent
 I & III are identical



1) Identity Element:

Identity Element: Identity Element obtained by 360° or 0° rotation. All molecule possess an identity element. It is an operation when performed in molecule results in an identical configuration. The identical configuration can be visualise into two ways.

① Rotation by 360° about an axis. Do not do anything to molecule i.e. C[∞] rotation. Thus it is unique element axis. If it is represented by E. e.g.



I & II are identical

Group : A group is a collection of elements which are interrelated according to certain rules

OR
A group is a collection of elements having certain properties in common which enable a wide variety of algebraic manipulations to be carried out on the collection. It should denote numbers, matrices, vectors and symmetry operations.

Order of group : The total no. of symmetry elements which is present in a group is called as order of group. It is represented by h .
In H_2O molecule point group is C_{2v} in C_{2v} point group order is 4 & in C_{2v} point group order is 6.

Sub-group : A subset of element of a group forming a group of smaller order is referred to as a sub-group.
OR
Smaller groups which may be found within a larger group are called sub-group.

e.g. In C_{2v} group there is E, C_2, σ_v are smaller groups.

Conjugacy relation and classes :

In order to understand classes in a group, similarly transformations of element should be appreciated. The group having element x, A & B the following relations may hold good.

$$X^{-1} A X = B$$

X^{-1} = Reciprocal of x in such a case

B is said to be a similarity transform of A by X or A & B are conjugate.

Conjugate elements having following properties

- ① Every element is conjugate to itself i.e. $(X^{-1}) A X = A$ where x is identity
- ② If A is conjugate with B , B must be conjugate with A .
- ③ i.e. if $(X^{-1}) A X = B$ Hence $B^{-1} X^{-1} X B = A$ i.e. B is another element of the group.

A is conjugated with B & C then B & C are conjugate with each other.

$$(X^{-1}) A X = B \quad \therefore B^{-1} X^{-1} X B = A$$

$$A^{-1} C = (X^{-1}) A X = B$$

$$A^{-1} C = (X^{-1}) A X = B$$

$$A^{-1} C = (X^{-1}) A X = B$$

$$A^{-1} C = (X^{-1}) A X = B$$

$$A^{-1} C = (X^{-1}) A X = B$$

Date

Student's Name

Class: A set of elements in a group which are conjugate to one another is said to form a class.

Let us perform the similarity transformation of the C_2 operation of H_2O molecule with all the other operations

$$E^{-1} C_2 E = C_2 \quad \sigma_v^{-1} C_2 \sigma_v = C_2 \\ (C_2)^{-1} C_2 C_2 = C_2 \quad (C_2)^{-1} C_2 C_2 = C_2$$

* Relation between orders of a finite group and its subgroup

Group containing finite number of elements is referred to as finite group whereas the infinite number of elements constitute infinite group ($h = \infty$). Consider finite group of order $h = 4$ i.e. $I, -I, i, -i$. The combining rule being algebraic multiplication = $i^2 = I$. The identity element is I and the inverse of I is $-I$ of i is $-i$ and of $-i$ is i etc.

Note that the group $(I, -I)$ is a part of larger group $I, -I, i, -i$. Thus $I, -I$ is said to be a subgroup of the group $I, -I, i, -i$. The order of the group is an integral multiple of its subgroup.

However, $i, -i$ is not a group since there is no identity element and the ring closure does not hold.

* Point symmetry group

All the symmetry operations in a molecule can be combined to form a molecular group. This p group is called the point group.

OR

The collection of all the symmetry operations of a single point molecule is known as point group or point symmetry. Order of a point group is represented by h where $h = \text{no. of symmetry elements present in the molecule}$. The molecular point groups are represented by the Schoenflies symbols.

Schoenflies Symbols

Each molecular point group is identified by a symbol known as Schoenflies notation. It consists of a capital letter and a subscript. There are

- C simple rotation axis perpendicular to principal axis
- D n fold rotation axis perpendicular to principal axis
- T symmetry based on tetrahedron
- O symmetry based on octahedron
- I symmetry based on icosahedron
- S only plane of symmetry
- ∞ only centre of symmetry
- n only n fold rotation axis
- nv Vertical symmetry plane or σ_{nv}
- nh horizontal symmetry plane or σ_h
- ∞ perpendicular to principal rotation axis
- ∞ dihedral symmetry plane or σ_d
- ∞ perpendicular to principal rotation axis

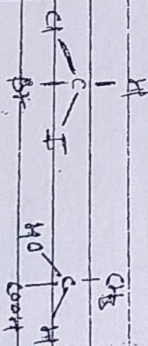
- ① molecules of low symmetry (containing less no. of sym. elements)
- ② molecules of high symmetry (contains more no. of sym. elements)
- ③ molecules with special symmetry (fairly identifiable)

Molecular

molecules can be divided into

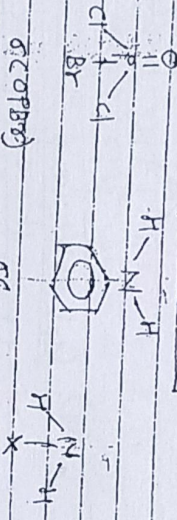
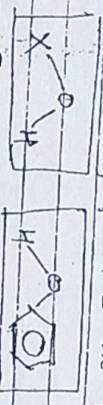
Molecules of low symmetry:

① C_1 : molecule with only C rotation axis
 element comes under C_1 point group
 order of group $h=1$ i.e. E or C_1
 e.g. All asymmetric molecule are the best example of point group C_1 .

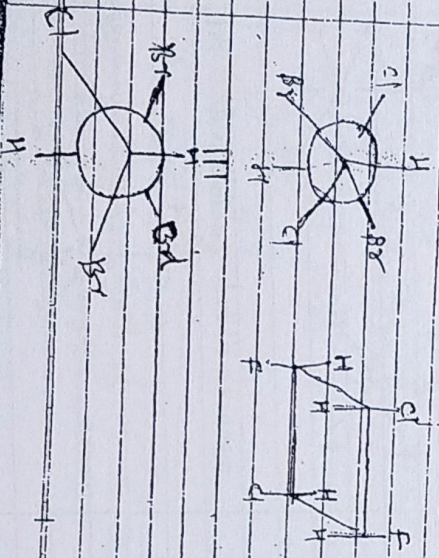


② C_2 Point group: molecule with only a plane of symmetry comes under C_2 point group.

Order of group $h=2$ i.e. E, C_2



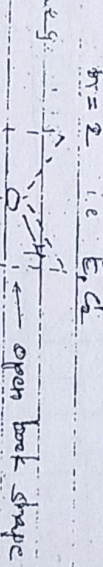
③ C_i point group: molecules with only centre of inversion comes under C_i point group. Order of group $h=2$ i.e. E, i . These molecules are very rare.



④ Molecules of high symmetry.

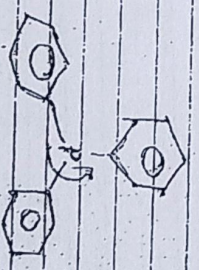
A) C_n point group :- If is a pure rotational group molecule with only C_n relation or order of group $h=n$.

D) C_2 point group :- $C_2 = 180^\circ$ rotation axis



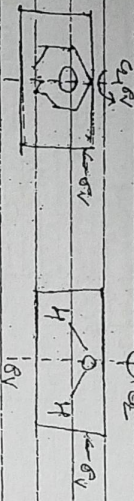
⑤ C_3 point group

$h=3$ i.e. E, C_3, C_3^2 . eg. NH_3, CH_3, NH_3 . $C_3 = 120^\circ$ rotation axis

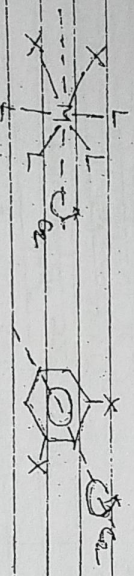


D) CNV point group : It contains C_n element & number of vertical plane order of group i.e. $h \cdot 2n$

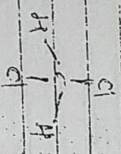
CH) C_{2v} $h=4$ i.e. $E, C_2, 2\sigma_v$
e.g. H_2O, H_2S, NO_2



B) cis disubstituted octahedral complex



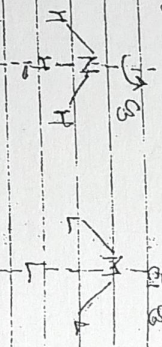
W) disubstituted tetrahedral complex



U) C_{nv} point group
 $h=6$ i.e. $E, C_2, C_3, 3\sigma_v$

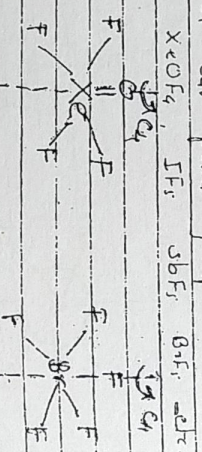
e.g. All pyramidal molecules i.e. trigonal pyramidal molecule

In NH_3 molecule C_3 axis as a principle rotational axis & 3 σ_v planes. Therefore it belongs to C_{3v} point group.

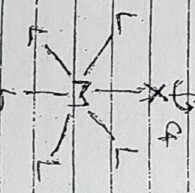


III) C_{4v} point group
If contains C_4 axis as the rotational axis

e.g. All square pyramidal molecules are $h=8$ i.e. $E, C_4, C_2, C_2', C_2'', 4\sigma_v$



monosubstituted octahedral ML_5X

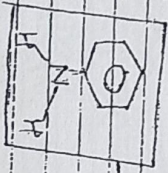


1) C_n point group

This point group contain C_n rotational axis horizontal plane & σ_h element order of group $h = 2n$
 If n is even this point group necessarily contain center of inversion (i)

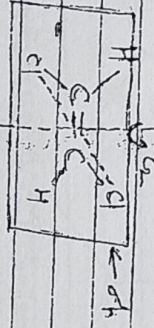
C_{2h} point group

order of group $h = 2$ i.e. E, σ_h
 It contains only plane of symmetry
 e.g. Aniline



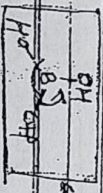
2) C_{2v} point group

$h = 4$ i.e. $E, C_2, \sigma_v, \sigma_v'$
 e.g. Trans dioxane ethylene



3) C_{3h} point group

$h = 6$ i.e. $E, C_3, C_2, \sigma_h, S_6, S_6^5$
 e.g. B(OH)3 Boric acid



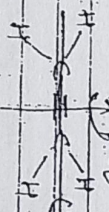
2) D_n point group

It is also a pure rotation point group. This point group consists of a C_n element, n number of C_2 & perpendicular C_2 elements $h = 2n$

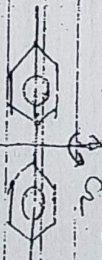
All gauche molecules come under D_n point group.

1) D_2 point group

In this point group has element i.e. E, C_2, C_2, C_2
 e.g. Gauche ethylene, Gauche biphenyl



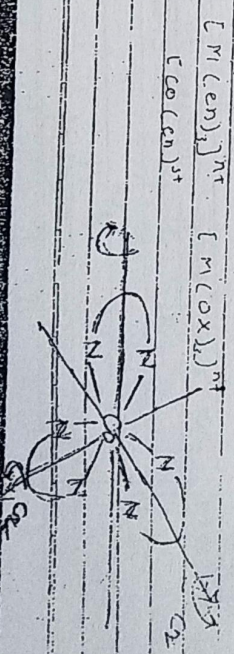
Gauche ethylene



Gauche biphenyl

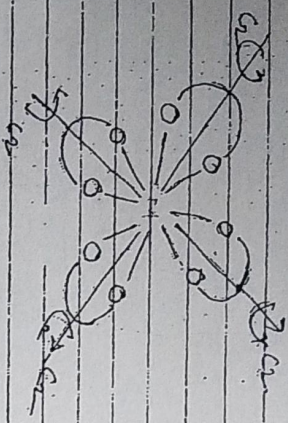
3) D_3 point group

$h = 6$ i.e. $E, C_3, C_2, C_3, C_2, C_3$
 e.g. All this symmetric bidentate metal complex



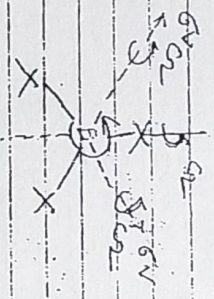
③ D_4 point group

$h=8$ i.e. $E, C_4, C_2, C_2', C_2'', C_2''', C_2''''$
 ex: Tetra symmetric bidentate complex

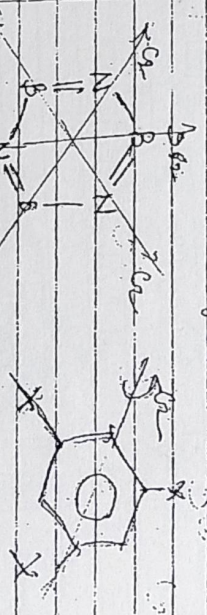


④ D_3h point group

$h=12$ i.e. $E, C_3, C_2, 3C_2', 3C_2'', 3C_2''', 3C_2''''$
 eg. All edipical molecules comes under D_3h point group. All trigonal planar molecule comes under D_3h point group. eg. BX_3, CH_3^+, NH_3



All trigonal bipyramidal molecule are comes under the point group eg PCl_5



⑤ D_4h point group:

$h=16$ i.e. $E, C_4, C_2, C_2', C_2'', 4C_2, 4C_2', 4C_2'', 4C_2''', 4C_2''''$
 eg. All square planar molecule comes under D_4h point group.

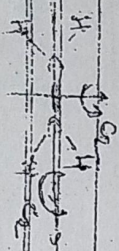


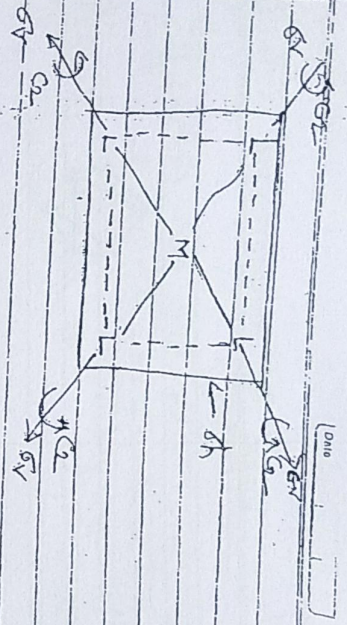
E) I_h point group:

This point group contain C_n rotational axis, n number of C_n perpendicular to C_n , n no. of vertical plane horizontal & $3n$ improper axis. If n is even this point group is necessary contain center of inversion (i)
 $h=2n$ element
 i.e. $C_n, nC_2, I, n\sigma_v, n\sigma_h, 3n$

① D_{2h} point group:

$h=8$ element i.e. $E, C_2, 2C_2', 2C_2'', \sigma_v, \sigma_h, S_2$
 eg. C_2H_2



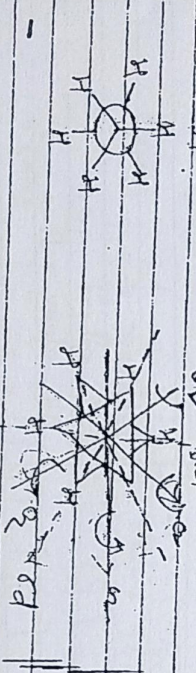


F) D_{6h} point group:

All staggered molecule
 comes under D_{6h} point group
 h = 6n

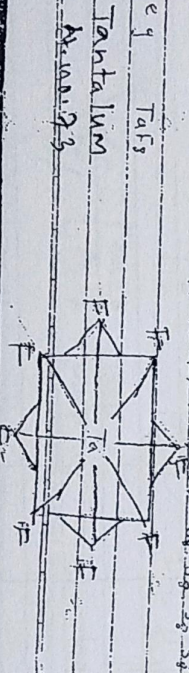
1) D_{3h} point group

h = 12 i.e. E, C₆, C₃, 3C₂, 3C₂, 3C₂, σ_h, σ_d, σ_d, σ_d, i



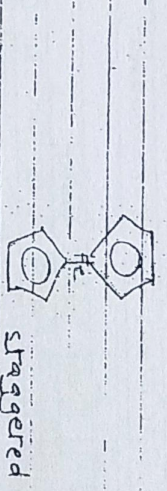
2) D_{4d} point group

h = 16 i.e. E, C₈, C₄, C₂, C₂, C₂, C₂, C₂, C₂, σ_h, σ_d, σ_d, σ_d, σ_d, σ_d, σ_d



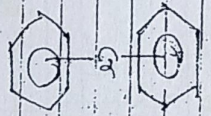
3) D_{5d} point group

h = 20 i.e. E, C₁₀, C₅, C₅, C₂, C₂, σ_h, σ_d, σ_d, σ_d, σ_d, σ_d, σ_d, σ_d, σ_d, σ_d, σ_d



4) D_{3d} point group

h = 12 i.e. E, C₆, C₃, C₂, C₂, C₂, σ_h, σ_d, σ_d, σ_d, σ_d, σ_d, σ_d, i



3) Molecules of special symmetry

Identified molecules which have special geometry come under the special symmetry
 e.g. D_{6h}, T_d, O_h, I_h, K_i

Conv point group:

$h=2$
 All non centrosymmetric linear molecule
 e.g. HCl, H_2O , CO, NO, HCN
 $H-C \equiv C-H$
 $X=C=S$, $X=C=O$ etc

D_{2h} point group

$h=2$ i.e. E, C_2 , σ , i
 e.g. All centre symmetric linear molecules
 Homodromic molecules
 $H_2, O_2, N_2, Cl_2, CO_2, S=C=S, N_2$

T_d point group

All tetrahedral molecules not chiral
 under this point group
 $h=24$ i.e. E, $8C_3, 3C_2, 6S_4, 6\sigma_d$
 It must be a pure tetrahedral
 e.g. $CH_4, BH_3, SO_2, PO_4, FeO_4^{2-}$



D_{3h} point group

$h=12$ i.e. E, $6C_2, 3C_3, 8C_2, 6C_3, 6S_6, 8S_6, 6\sigma_d$
 These molecule with 48 symmetry element
 comes under oh point group

I_h point group



I_h point group

$h=120$
 All icosahedral or dodecahedral
 e.g. $24C_5, 20C_3, 15C_2, 24S_6, 20S_10, 15\sigma_d$
 120 corners
 20 triangular faces
 30 edges
 e.g. $B_{12}H_{12}^{2-}$, C₆₀ fullerene, C₅₀ fullerene
 cube fullerene
 K_h point group
 Sphere group
 All atoms $h=24$

* Matrix representation of groups

A matrix is a rectangular array of numbers or symbols for numbers. The set of matrices corresponding to the symmetry operations of a group is called its representation.

Matrix representation of symmetry operations

(1) Matrix for the identity operation

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

(2) Reflection operations :- Principal Cartesian Plane i.e. (xy),

$$\sigma(xy) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ y \\ -z \end{bmatrix}$$

$$\sigma(xz) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ -y \\ z \end{bmatrix}$$

$$\sigma(yz) = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -x \\ y \\ z \end{bmatrix}$$

OR

$$\sigma = \begin{bmatrix} \cos 2\theta & \sin 2\theta & 0 \\ \sin 2\theta & -\cos 2\theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(3) Inversion operation

$$I = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

(4) Rotation

$$C_n = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ or } \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(5) Improper rotation

$S_n = C_n \times \sigma(xy)$ for xy plane

$$S_n = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \cos \theta + y \sin \theta \\ -x \sin \theta + y \cos \theta \\ -z \end{bmatrix}$$

$$S_n(xy) = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \cos \theta + y \sin \theta \\ -x \sin \theta + y \cos \theta \\ z \end{bmatrix}$$

$$S_n(yz) = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ \sin \theta & -\cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \cos \theta + y \sin \theta \\ -x \sin \theta + y \cos \theta \\ z \end{bmatrix}$$

$$S_n(xz) = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ \sin \theta & -\cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \cos \theta + y \sin \theta \\ -x \sin \theta + y \cos \theta \\ z \end{bmatrix}$$

① Matrix representation of symmetry operations of the point group C_{2v}

Point group C_{2v}

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad C_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad \sigma_v = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad \sigma_v' = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

② Matrix representation of symmetry operations in C_{2v} group.

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad C_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad \sigma_v = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad \sigma_v' = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Also $\sigma_{xy} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$ $\sigma_{yz} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

③ Matrix representation of symmetry operations in C_{3v} group

in C_{3v} group

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad C_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ 0 & \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{bmatrix} \quad C_3^2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & -\frac{\sqrt{3}}{2} \\ 0 & \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{bmatrix}$$

$\sigma_v = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$ $\sigma_v' = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ $\sigma_v'' = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$

Representation for C_{2v} point group

For C_{2v} group possible symmetry operations are $E, C_2, \sigma_v(xz), \sigma_v'(yz)$ combination of E with single column matrix leaving 1 unchanged as below

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad C_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad \sigma_v(xz) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad \sigma_v'(yz) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Matrix representation for C_2 operations can similarly be worked out

$$C_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad \sigma_v(xz) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad \sigma_v'(yz) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

similarly for $\sigma_v(xz)$ operation

$$\sigma_v(xz) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ y \\ -z \end{bmatrix}$$

similarly for $\sigma_v'(yz)$ operation

$$\sigma_v'(yz) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -x \\ y \\ z \end{bmatrix}$$

The combination of two operation of H_2O molecule can show combination of matrices i.e.

$$C_2 \times \sigma_v(xz) = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -1+0 & 0+0 & 0+0 \\ 0+0 & 0+1 & 0+0 \\ 0+0 & 0+0 & 0+1 \end{bmatrix}$$

$$= \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$C_2 \times \sigma_v(xz) = \sigma_v(yz)$$

Multiplication table of H₂O i.e. can point group is as follow

σ_v	E	C_2	$\sigma_v(xz)$	$\sigma_v(yz)$
E	E	C_2	$\sigma_v(xz)$	$\sigma_v(yz)$
C_2	C_2	E	$\sigma_v(yz)$	$\sigma_v(xz)$
$\sigma_v(xz)$	$\sigma_v(xz)$	$\sigma_v(yz)$	E	C_2
$\sigma_v(yz)$	$\sigma_v(yz)$	$\sigma_v(xz)$	C_2	E

Inv. case of character table

	E	C_2	$\sigma_v(xz)$	$\sigma_v(yz)$
E	1	1	1	1
C_2	1	1	-1	-1
$\sigma_v(xz)$	1	-1	1	-1
$\sigma_v(yz)$	1	-1	-1	1

Representation of Character table

Representation is divided into two main types

- ① Reducible representation
- ② Irreducible representation

Reducible Representation

Representation of higher dimension which can be reduced into representation of lower dimension known as reducible representation for given molecule. Here can see number of reducible representation. Reducible representation can be understood by considering symmetry transformation. A, B, C, D by applying similarity transform condition for each matrix representation.

$$[X^{-1}] A [X] = A$$

$$[X^{-1}] \begin{bmatrix} A_1 & & \\ & A_2 & \\ & & A_3 \end{bmatrix} [X] = \begin{bmatrix} A_1 & & \\ & A_2 & \\ & & A_3 \end{bmatrix}$$

Block factored A.

$$[X^{-1}] \begin{bmatrix} a_1 & & \\ & a_2 & \\ & & a_3 \end{bmatrix} [X] = \begin{bmatrix} a_1 & & \\ & a_2 & \\ & & a_3 \end{bmatrix}$$

Block factored B matrix

$$[X^{-1}] \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} [X] = \begin{bmatrix} c'_1 \\ c'_2 \\ c'_3 \end{bmatrix}$$

block diagonal 'c'
matrix

$$[X^{-1}] \begin{bmatrix} D_1 & & \\ & D_2 & \\ & & D_3 \end{bmatrix} [X] = \begin{bmatrix} D'_1 & & \\ & D'_2 & \\ & & D'_3 \end{bmatrix}$$

block diagonal 'D'
matrix

$$[B][C] = D$$

$$[A][C] = D'$$

$$[B_2][C_2] = D_2$$

$$[B_1][C_1] = D_1$$

If shows that for given molecule there can be only number of reducible representation

(iii) Irreducible representation:

Representation

which can not be reduced into other lower representation is known as

irreducible representation

For given point group a final number of irreducible representation only possible

Types of groups:

* (i) Abelian group:

A abelian group is one in which all the elements commute with each other. The elements which follow the commutative law of multiplication) e.g. A, B, C are the elements of a group

$$A \cdot B = C$$

$$B \cdot A = C$$

Then A & B element said to be commutative if each other

e.g. Gay point group

In Gay, $h = 4$ i.e. E, C₂, σ_v, σ'_v

$$E \times C_2 = C_2$$

$$C_2 \times E = C_2$$

$$\sigma_v \times \sigma'_v = C_2$$

$$\sigma'_v \times \sigma_v = C_2$$

$$C_2 \times \sigma_v = \sigma'_v$$

$$\sigma_v \times C_2 = \sigma'_v$$

$$\sigma'_v \times \sigma'_v = E$$

$$\sigma_v \times \sigma_v = E \quad \text{e.g. H}_2O$$

* (ii) Non abelian groups:

Non abelian group is one in which the element map not commute to each other. The elements may not follow the commutative law of multiplication.

e.g. A, B, C, D are the elements in a group

A.B = C
B.A = D

A, B said to be non commutative

e.g. Cay point group

In Cay, $h = e, i, e, E, G, G^2, \sigma, \sigma^2$

$G^3, G^4 = G^0 = E$

$G^2, G^3 = G^1 = E$

$G^4, G^5 = \sigma, \sigma^2$

e.g. NH₃

③ Isomorphic groups:

If two groups have the same

order and if the forms of their

multiplication tables are the same, the

groups are said to be isomorphic and

this simplifies the construction of

character tables.

Following point groups are isomorphic

$C_{nv} \sim D_n, C_{nh} \sim C_n$ (n even), $C_{nh} \sim C_n$ (n odd)

$D_{nd} \sim D_{nd}, D_{nh} \sim D_{nd}$ (n odd)

$O \sim T_d$

e.g. C_{nv} and D_n have the same

character table, although their symmetry

operations are different.

IMB

* Great Orthogonality Theorem (GOT)

The relationship between the elements

of unitary matrices to form group representation is given by Great Orthogonality

Theorem. As the name indicates, the

the theorem shows orthogonal relationships

that exist between the matrix elements

of the different representations of a

group.

Mathematically, it is stated as

$$\sum_{R \in G} [\Gamma(R)_{mn}] [\Gamma'(R)_{pq}]^* = \frac{h}{|G|} \delta_{ij} \delta_{kl}$$

h = order of the group
|G| = dimension of the representation of the group

i, j & k, l = dimension of two irreducible representations of the group

R = various symmetry operations of the group

m and n represents m^{th} row & n^{th} column of the matrix

* represents the complex conjugate

δ is Kronecker delta $\delta_{ij} = 0$ if $i \neq j$

and $\delta_{ij} = 1$ if $i = j$

Each element is normalized & orthogonal

to the other element in the matrix

The character of the i^{th} representation

of operation R , is just the sum of

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The diagonal elements of the matrix representing R .

The equation (1) can be put in three simpler equation

If $i \neq j$ $d_{ij} = 0$ and $m = m'$ and $n = n'$ Then

$$\sum_R \Gamma_i(R) \Gamma_j(R) = 0$$

$$\text{or } \sum_R \Gamma_i(R) \Gamma_j(R) = 0$$

Elements corresponding to matrices of different irreducible representation are orthogonal

(2) If $m \neq m'$ and $n \neq n'$ $d_{mm} = 0$ & $d_{nn} = 0$

Then

$$\sum_R \Gamma_i(R) \Gamma_j(R) = 0$$

Elements of the different sets of the matrices of the same IR_i are orthogonal

(3) If $i = j$, $m = m'$ and $n = n'$ $d_{ii} = 1$.
 $d_{mm} = 1$ Then

$$\sum_R \Gamma_i(R) \Gamma_i(R) = \frac{h}{k}$$

where $h =$ order of group
 $k =$ dimensional length

* Importance of Great Orthogonality Theorem

following rules can be derived from GOT for irreducible representation of a group

(1) The number of irreducible representation in a group is equal to number of classes of operation of groups.

(2) The sum of the squares of the dimension of the irreducible representations is equal to the order of the point group.

$$\sum_i h_i^2 = 1^2 + 1^2 + 3^2 + \dots = h$$

where the summation is taken over all the representations Γ_i . Since the dimension of IR is equal to the character of the identity operation E , so that sum of the squares of the character of E of IR_i of group is equal to the order of group

$$\sum_i [\chi_i(E)]^2 = h$$

(3) The sum of the square of the character of an irreducible representation is equal to the order of the group.

$$\sum_i [\chi_i(E)]^2 = h$$

(4)

The characters of the same irreducible rep. are same

$$\sum_i \chi_i(R)$$

(1) The character same class or reducible

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(4) The characters of the irreducible representations of the same group are orthogonal to each other. i.e. the columns of the reducible representations in the character table form orthogonal vectors.

$$\sum_i \chi_i(R) \chi_j(R) = 0$$

(5) The characters of the elements of the same class of an irreducible representation or reducible representation are same.

Notations for irreducible representations or Mulliken symbol

(1) Dimensions of the irreducible representations

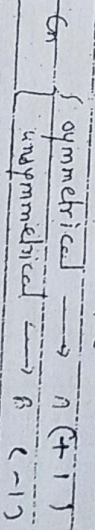
If the dimension of the irreducible representation is unidimensional term A or B is used i.e.

- A or B → one dimensional
- E → two dimensional
- T → three dimensional
- G → four dimensional

(2) Symmetry with respect to principle axis

If the one dimensional irreducible representation is symmetrical with respect to principle axis in C_v the character

in operation is +1 term A is used with respect to principle axis (character of is -1) term -1 is used i.e.



(3) Symmetry with respect to subsidiary axis:

If the (IR) irreducible representation is symmetrical with respect to the subsidiary axis subscript A, B, E, & T, are used & if it is unsymmetrical subscript A₂, B₂, E₂ & T₂ are used

subsidary axis $\left\{ \begin{array}{l} \text{symmetrical} \rightarrow A_1, B_1, E_1, T_1 \\ \text{unsymmetrical} \rightarrow A_2, B_2, E_2, T_2 \end{array} \right.$

Symbol for centre of symmetry

If there is center of symmetry in the molecule subscript 'g' is used for symmetry and 'u' is used for antisymmetry.

$\left\{ \begin{array}{l} \text{symmetry} \rightarrow g \\ \text{antisymmetry} \rightarrow u \end{array} \right.$

For a symbol with a prime (') character +1 must appear for sh and for symbol with double prime (") character -1 is used for sh i.e.

$\left\{ \begin{array}{l} \text{single prime (')} \rightarrow +1 \\ \text{double prime ('')} \rightarrow -1 \end{array} \right.$

* Character table for O_h point group:

point group:

In O_h point group there are four operations of four different classes E, G_4, G_2, G_3 & G_6

In O_h point group there are four classes of operations, there are four irreducible representations, i.e. $\Gamma_1, \Gamma_2, \Gamma_3$ & Γ_4

The sum of squares of dimension of irreducible representation should be equal to 4. Hence each representation must be unidimensional i.e.

$$1^2 + 1^2 + 1^2 + 1^2 = 4$$

since, dimensions of representation is equal to the character of identity the operation of irreducible representation E must be equal to 1 in all of them.

Char	E	G_4	G_2	G_3	G_6
Γ_1	1				
Γ_2	1				
Γ_3	1				
Γ_4	1				

The sum of squares of the characters of an irreducible representation must be equal to 4. For one of the irreducible.

Date

representation (Γ) all characters must be equal to 1 i.e.

Γ_1	E	C_2	σ_{xz}	σ_{yz}
Γ_2	1	1	1	1

i.e. $1^2 + 1^2 + 1^2 = 4$

Q4 In case of other irreducible representation

also the sum of squares of characters equal to 4 and characters must be orthogonal. Thus the character must be ± 1 and $\pm i$ and $\pm i$

The irreducible representation with their characters shown as follows

Γ_1	E	C_2	σ_{xz}	σ_{yz}
Γ_2	1	1	1	1
Γ_3	1	1	-1	-1
Γ_4	1	-1	1	-1
Γ_5	1	-1	-1	1

Q5 Γ_1 is one dimensional, symmetrical to the principle axis and the vertical plane axes

Hence symbol is A_1 , Γ_2 is undimensional but unsymmetrical to σ_{xz} Hence symbol is A_2 .

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Γ_3 is undimensional unsymmetrical with respect to principle axis but symmetrical with respect to σ_{xz} Hence symbol is B_1 . Γ_4 is undimensional unsymmetrical to the principle axis and also unsymmetrical to σ_{xz} Hence symbol is B_2 .

Therefore the complete character table for C_{2v} point group is

Γ_1	E	C_2	σ_{xz}	σ_{yz}
A_1	1	1	1	1
A_2	1	1	-1	-1
B_1	1	-1	1	-1
B_2	1	-1	-1	1

Construction of character Table for point group element $E, C_2, \sigma_{xz}, \sigma_{yz}$

There are four point group has 6 half classes of operations are there therefore in C_{2v} three irreducible representations are present. i.e. Γ_1, Γ_2 & Γ_3

Q6 The sum of squares of the dimension should be equal to the S since the dimension has to be an integer, there should be two one dimensional & one two dimensional.

G_3	E	2G	3Gv
Γ_1	1		
Γ_2	1		
Γ_3	2		

① $1 \cdot 1^2 + 1^2 + 2^2 = 6$

② It can be seen that the summation of squares of characters of operation is equal to 6

G_3	E	2G	3Gv
Γ_1	1	1	1

1 x (1)² + 2 x (1)² + 3 x (1)² = 6

③ The characters of Γ_1 & Γ_2 are orthogonal. Hence the characters G_3 & G_v for Γ_2

when $G_3 = 1$ & $G_v = -1$ eqn is correct

i.e. $1 + 2 - 3 = 0$

G_3	E	2G	3Gv
Γ_1	1	1	1
Γ_2	1	1	-1
Γ_3	2	G	Gv

The characters of Γ_3 are orthogonal to Γ_1 & Γ_2

Let $G_3 = 0$
 $G_v = 1$

Orthogonality theorem betn Γ_1 & Γ_3

$1 \cdot 1 \cdot 2 + 2 \cdot 1 \cdot G_3 + 3 \cdot 1 \cdot G_v = 0$
 $2 = 0$

G_3	E	2G	3Gv
Γ_1	1	1	1
Γ_2	1	1	-1
Γ_3	2	-1	0

Γ_1 is one dimensional, symmetrical to principle axis & to the vertical plane hence symbol A_1 is assigned.

Γ_2 is one dimensional & symmetrical to principle axis but unsymmetrical with respect to vertical plane so symbol A_2 is used. Γ_3 is two dimensional so symbol E is used. Hence complete character table for G_v

G_3	E	2G	3Gv
A_1	1	1	1
A_2	1	1	-1
E	2	-1	0

* Construction of character table for C_{2h} point group

In C_{2h} point group there are two different classes i.e. $h=2$ which are E, σ_h

① Since there are ~~two~~ ^{two} classes of operation there are two irreducible representations i.e. Γ_1 & Γ_2

② The sum of squares of dimensions of irreducible representation should be equal to 2. Hence each representation must be unidimensional

$$n_1^2 + n_2^2 = 2$$

C_{2h}	E	σ_h
Γ_1	1	
Γ_2	1	

③ The sum of squares of the characters of an irreducible representation must be equal to 2.

C_{2h}	E	σ_h
Γ_1	1	1
Γ_2	1	-1

$$1^2 + 1^2 = 2$$

④ Character of irreducible representations of a group are orthogonal to the each other.

$$1 \cdot 1 + 1 \cdot 1 \cdot \sigma_h = 2$$

$$1 + \sigma_h = 0$$

C_{2h}	E	σ_h
Γ_1	1	1
Γ_2	1	-1

Γ_1 is unidimensional & symmetrical rep'd to σ_h . Hence A_1 is used. Γ_2 is unidimensional & unsymmetrical rep'd to σ_h . Hence A_2 is used.

C_{2h}	E	σ_h
A_1	1	1
A_2	1	-1

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* Character tables and their use :

For a point group whenever the symmetry elements and the irreducible representation are arranged along with their character in the form of table, containing rows & column is known as character table.

It consist of four columns. Character tables of molecular point groups are extremely important for their applications in solving chemical problems related to molecular spectroscopy.

Character tables find their extensive use in

- ① symmetry properties of orbitals
- ② Hybrid molecular orbital theory
- ③ Electronic transitions
- ④ Infrared & Raman active vibrations
- ⑤ structure elucidation of molecules.

* Applications of group theory :

① Group theory is an extremely useful tool to predict the probability of transitions in atomic & molecular spectroscopy.

② If helps in the classification of the normal vibrations according to the irreducible representations of the point group of molecule.

③ It aids in qualitatively finding out the infrared & Raman spectral activity of the fundamental as well as the overtone combinations bands.

④ Group theory can be applied in the construction of hybrid orbitals & symbols adopted linear combination of atomic orbitals in MO.

⑤ Group theory helps in determining optical activity and polarity of molecules, Classification of elementary particles into fermion & boson and simplifying the secular equation, which is a special feature of the quantum mechanical calculations in both VBT and MOT.